



ẤN PHẨM THÔNG TIN THƯ MỤC THEO CHUYÊN NGÀNH

Ứng dụng robot trong công nghiệp/nông nghiệp. Chuyên ngành Cơ điện tử thông minh (Trường Cơ khí)

Ấn phẩm bao gồm link các tài liệu điện tử theo từ khóa:

Ứng dụng robot trong công nghiệp/nông nghiệp = Applications of robots in industry/agriculture

STT	Tên tài liệu	Nguồn CSDL	Loại tài liệu	Ghi chú
1	Influence of different parameters on drilling forces in automated drilling	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
2	Deliberative safety for industrial intelligent human–robot collaboration	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
3	Experimental and numerical assessments of new concrete dry connect	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
4	An autonomous rail-road amphibious robotic system for railway main	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
5	Robot-assisted laser ablation for 3D surfaces. Application for paint re	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
6	A railway track reconstruction method using robotic vision on a mobi	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
7	Areas investigated when initiating OEM remanufacturing – a case of	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
8	Coupled Dynamic Simulator With Tri-Dexel Milling Module For Rol	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
9	Robotic friction stir welding in lightweight battery assembly of extrus	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
10	Instance segmentation based 6D pose estimation of industrial objects	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
11	Cyber-Physical Optimization of Production Processes Using Two AIs	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
12	Modelling the influence of material and process parameters on Shotc	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
13	Towards seamless collaboration of humans and high-payload robots:	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
14	Design and development of a low-cost 5-DOF robotic arm for lightwe	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến

15	Guidelines for the integration of cognitive ergonomics in the design of	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
16	A method for understanding and digitizing manipulation activities usi	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
17	Specification, stochastic modeling and analysis of interactive service	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
18	Mapping socio-technical dependencies to enable the successful adopt	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
19	Design of electric vehicles for Industry 4.0: the case of an Autonomo	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
20	Component-based robot prefabricated construction simulation using I	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
21	A configurable process control method for robotic system-based indu	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
22	High airflow vertical conveying gripper for robotic sorting of shredde	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
23	Zero programming robotics in additive manufacturing repairs	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
24	Live semantic data from building digital twins for robot navigation: C	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
25	A framework for multi-robot control in execution of a Swarm Produc	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
26	A multiobjective decision-making approach for modelling and planni	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
27	An autonomous biodegradable hygroscopic seed-inspired soft robot fo	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
28	Real-time optimization for a Digital Twin of a robotic cell with huma	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
29	Industrial Cross-Robot Transfer Learning	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
30	Towards Robot-Assisted Data Generation with Minimal User Interact	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
31	Development of robot assisted hybrid additive manufacturing technol	Science Direct	Research article	Tài toàn văn/Độc trực tuyến
32	Research on the impact of industrial robot application on the status of	ProQuest Central	Scholarly Journal	Tài toàn văn/Độc trực tuyến
33	Mobile Robot for Security Applications in Remotely Operated Advan	ProQuest Central	Scholarly Journal	Tài toàn văn/Độc trực tuyến
34	Evaluating the Reliability of a Machine Vision System for Collaborat	ProQuest Central	Scholarly Journal	Tài toàn văn/Độc trực tuyến

35	Collaborative Behavior for Non-Conventional Custom-Made Robotic	ProQuest Central	Scholarly Journal	Tài toàn văn/Đọc trực tuyến
36	A Path to Industry 5.0 Digital Twins for Human–Robot Collaboration	ProQuest Central	Scholarly Journal	Tài toàn văn/Đọc trực tuyến
37	Toward Optimal Robot Machining Considering the Workpiece Surface	ProQuest Central	Scholarly Journal	Tài toàn văn/Đọc trực tuyến
38	A Perspective on Miniature Soft Robotics: Actuation, Fabrication, Co	ProQuest Central	Scholarly Journal	Tài toàn văn/Đọc trực tuyến
39	Real-Time Performance Benchmarking of RISC-V Architecture: Imp	ProQuest Central	Scholarly Journal	Tài toàn văn/Đọc trực tuyến
40	Research on the System Design and Target Recognition Method of th	ProQuest Central	Scholarly Journal	Tài toàn văn/Đọc trực tuyến
41	Application of reinforcement learning algorithm on robot motion con	ProQuest Central	Scholarly Journal	Tài toàn văn/Đọc trực tuyến
42	Recent Progress in Robot Control Systems: Theory and Applications	ProQuest Central	Scholarly Journal	Tài toàn văn/Đọc trực tuyến
43	Robot operating system based autonomous navigation platform with l	ProQuest Central	Scholarly Journal	Tài toàn văn/Đọc trực tuyến
44	Adaptive Sliding Mode Resilient Control of Multi-Robot Systems wi	ProQuest Central	Scholarly Journal	Tài toàn văn/Đọc trực tuyến
45	Integrating Function Allocation and Operational Event Sequence Diag	Sage Journal	Research article	Tài toàn văn/Đọc trực tuyến
46	Single-layer neural-network based control of agricultural mobile robo	Sage Journal	Research article	Tài toàn văn/Đọc trực tuyến
47	Research on the application of impedance control in flexible grasp of	Sage Journal	Research article	Tài toàn văn/Đọc trực tuyến
48	Modeling contact forces during human-robot interactions for perform	Sage Journal	Research article	Tài toàn văn/Đọc trực tuyến
49	A low-cost single-motor-driven climbing robot based on overrunning	Sage Journal	Research article	Tài toàn văn/Đọc trực tuyến
50	An integrated intuitionistic dense fuzzy Entropy-COPRAS-WASPAS	Sage Journal	Research article	Tài toàn văn/Đọc trực tuyến
51	A coverage path planning approach for autonomous radiation mappin	Sage Journal	Research article	Tài toàn văn/Đọc trực tuyến
52	Design and control of underwater robot system for sea cucumber fish	Sage Journal	Research article	Tài toàn văn/Đọc trực tuyến
53	Research on path planning of tea picking robot based on ant colony al	Sage Journal	Research article	Tài toàn văn/Đọc trực tuyến
54	RoBUTCHER: A novel robotic meat factory cell platform	Sage Journal	Research article	Tài toàn văn/Đọc trực tuyến

55	Robot Drama: Investigating Frictions between Vision and Demonstration	Sage Journal	Research article	Tải toàn văn/Đọc trực tuyến
56	A robot path planning method using improved Harris Hawks optimization	Sage Journal	Research article	Tải toàn văn/Đọc trực tuyến
57	Do robots really destroy jobs? Evidence from Europe	Sage Journal	Research article	Tải toàn văn/Đọc trực tuyến
58	Robust servo linear quadratic regulator controller based on state compensation	Sage Journal	Research article	Tải toàn văn/Đọc trực tuyến
59	Application of metal rubber for semi-active vibration control of mechanical systems	Sage Journal	Research article	Tải toàn văn/Đọc trực tuyến
60	Replacing cheap nature? Sustainability, capitalist future-making and the robot	Sage Journal	Research article	Tải toàn văn/Đọc trực tuyến
61	Energy consumption optimization for sustainable flexible robotic cell	Sage Journal	Research article	Tải toàn văn/Đọc trực tuyến
62	Discrete open-closed-loop PID-type iterative learning control for trajectory tracking	Sage Journal	Research article	Tải toàn văn/Đọc trực tuyến
63	Maintaining innovation: How to make sewer robots and innovation possible	Sage Journal	Research article	Tải toàn văn/Đọc trực tuyến

Tham khảo hướng dẫn:

1- *Hướng dẫn sử dụng ấn phẩm:*

2- *Hướng dẫn sử dụng tài khoản:*

[Hướng dẫn khai thác thư mục tài liệu điện tử theo chuyên ngành](#)

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