ẤN PHẨM THÔNG TIN THƯ MỤC THEO CHUYÊN NGÀNH

Máy bay không người lái. Chuyên ngành Cơ học vật bay (Trường Cơ khí)

Ấn phẩm bao gồm link các tài liệu điện tử theo từ khóa: Máy bay không người lái = Unmanned aerial vehicle

STT	Tên tài liệu	Nguồn CSDL	Loại tài liệu	Ghi chú
1	A corridor-based flight mode transition strategy for agile ducted-fan tail-s	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
2	A framework for preventing unauthorized drone intrusions through radar	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
3	A method to interpret fracture aperture of rock slope using adaptive shape	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
4	A self-adjusting multi-objective control approach for quadrotors	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
5	An enlarged polygon method without binary variables for obstacle avoida	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
6	Analysis of the impact of traffic density on training of reinforcement learn	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
7	Closed-loop nonlinear optimal control design for flapping-wing flying rob	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
8	Concept design and energy balance optimization of a hydrogen fuel cell h	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
9	Constrained docking control for shipborne UAV SideArm recovery	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
10	Contributions to data transmission at critical moments on unmanned aeria	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
11	Cooperative trajectory optimization of UAVs in approaching stage using	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
12	Cooperative UAV search strategy based on DMPC-AACO algorithm in r	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
13	Coverage and throughput analysis of an energy efficient UAV base statio	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
14	Deep reinforcement learning-based model-free path planning and collisio	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
15	Deep-reinforcement-learning-based UAV autonomous navigation and col	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
16	Design and fabrication of a fixed-wing Unmanned Aerial Vehicle (UAV)	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến

17	Design and stabilization of a Coandă effect-based UAV: Comparative stu	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
18	Digital twin modeling of open category UAV radio communications: A c	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
19	Electromagnetic interference modeling and elimination for a solar/hydrog	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
20	Elliptical encirclement control capable of reinforcing performances for U	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
21	Energy-minimizing 3D circular trajectory optimization of rotary-wing UA	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
22	Evaluation of different FW-H surfaces and modal decomposition techniq	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
23	Experimental investigation on turbulence effects on unsteady aerodynami	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
24	Fast UAV path planning in urban environments based on three-step exper	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
25	FFP: A Force Field Protocol for the tactical management of UAV conflict	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
26	Geometrically compatible integrated design method for conformal rotor a	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
27	GREENSKY: A fair energy-aware optimization model for UAVs in next-	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
28	Ground threat prediction-based path planning of unmanned autonomous h	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
29	Improved airborne computer system strategy for swarm drones flying base	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
30	Improved lazy theta∗ algorithm based on octree map for path planning of	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
31	Improvement of a multi-rotor UAV flight response simulation influenced	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
32	Influence of passive deformation in the lift coefficient of a NACA0012 w	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
33	Multi-UAV trajectory planning for 3D visual inspection of complex struc	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
34	New multi-UAV formation keeping method based on improved artificial	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
35	Nonlinear tight formation control of multiple UAVs based on model pred	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
36	Numerical analysis of a biomimetic UAV with variable length grids wing	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
37	On-field noise measurements and acoustic characterisation of multi-rotor	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
38	Optimal deployment of swarm positions in cooperative interception of mu	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến

39	Optimization of jamming formation of USV offboard active decoy cluste	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
40	Predefined-time formation control of the quadrotor-UAV cluster' positio	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
41	Progress in artificial intelligence-based visual servoing of autonomous un	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
42	Progress in modeling and control of probe-and-drogue autonomous aerial	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
43	Radar/visual fusion with fuse-before-track strategy for low altitude non-c	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
44	Reinforcement learning based UAV formation control in GPS-denied env	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
45	Ship trajectory prediction based on machine learning and deep learning: A	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
46	Soil methane emission suppression control using unmanned aircraft vehic	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
47	Spatio-temporal correlation-based multiple regression for anomaly detecti	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
48	Static aeroelasticity of the propulsion system of ion propulsion unmanned	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
49	Suggestions for flying qualities requirements of autonomous control unm	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
50	Thermodynamics, environmental damage cost, exergoeconomic, life cycl	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
51	Transition control of a tail-sitter unmanned aerial vehicle with L1 neural	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
52	Transportation Engineering	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
53	Unmanned aerial vehicle implementation for pavement condition survey	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
54	Unmanned aerial vehicle strike on a flat plate: Tests and numerical simul	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
55	Unmanned aerial vehicles towards future Industrial Internet: roles and op	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến
56	Wind disturbance compensated path-following control for fixed-wing UA	Science Direct	Research article	Tải toàn văn/Đọc trực tuyến

Tham khảo hướng dẫn:

1- Hướng dẫn sử dụng ấn phẩm: Hướng dẫn khai thác thư mục tài liệu điện tử theo chuyên ngành

2- Hướng dẫn sử dụng tài khoản: https://library.hust.edu.vn/vi/node/49